Lecture 1: Introduction to Spatial Econometric

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   - Goals and Mandatory Reading
   - Why do We Need Spatial Econometric?
   - Spatial Heterogeneity and Dependence
   - Spatial Autocorrelation

2 Spatial Weight Matrix
   - Definition
   - Weights Based on Boundaries
   - From Contiguity to the $W$ Matrix
   - Weights Based on Distance
   - Row Standardization
   - Spatial Lag
   - Higher-Order Spatial Neighbors

3 Examples of Weight Matrices in R
   - Creating Contiguity Neighbors
   - Creating Distance-Based

4 Testing for Spatial Autocorrelation
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Goals of this Lecture

- To understand the concept of spatial heterogeneity and spatial autocorrelation.
- To understand the concept of the Spatial Weight Matrix \( W \).
- To learn how to obtain the spatial weight matrices in \( \mathbf{R} \).
- To derive and understand the main test for spatial autocorrelation.
- To learn how to perform the Moran’s \( I \) test in \( \mathbf{R} \).
Reading for: Introduction to Spatial Econometrics

- (A) - Chapter 2
- (LK)-Sections 1.1-1.2
- (A)-Chapter 3
- (AR)-Chapter 3 and 4.


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- Important aspect when studying spatial units (cities, regions, countries)
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  - Potential relationships and interactions between them.
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- Example: Modeling pollution:
  - An increase in region $i$'s pollution will affect the pollution in neighboring regions, but the impact will be lower for more distant regions.
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  - Existence of environmental externalities:
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  - Existence of environmental externalities:
    - an increase in \( i \)'s pollution will affect the pollution in neighbors regions, but the impact will be lower for more distance regions.
Figure: Environmental Externalities

R1 ← R2 ← R3 → R4 → R5
Key Point:
First law of geography of Waldo Tobler: “everything is related to everything else”, but near things are more related than distant things.

This first law is the foundation of the fundamental concepts of spatial dependence and spatial autocorrelation.

Figure: Professor Waldo Tobler
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Why do We Need Spatial Econometric?

- Spatial econometric deals with **spatial effects**
  
  (I) Spatial heterogeneity

**Definition (Spatial heterogeneity)**

Spatial heterogeneity relates to a **differentiation** of the effects of space over the sample units. Formally, for spatial unit $i$:

\[ y_i = f(x_i) + \epsilon_i \quad \Rightarrow \quad y_i = \beta_i x_i + \epsilon_i \]

Lack of stability over the geographical space.
Why do We Need Spatial Econometric?

- Spatial econometric deals with spatial effects

  (II) Spatial dependence

Definition (Spatial dependence)
What happens in \( i \) depends on what happens in \( j \). Formally,

\[
y_i = f(y_i, y_j) + \epsilon_i, \forall i \neq j.
\]
How would you model this situation?

**Figure:** Environmental Externalities

```
R1  R2  R3  R4  R5
```

Spatial Dependence
Spatial Dependence

Using our previous example, we would like to estimate

\[ y_1 = \beta_{21} y_2 + \beta_{31} y_3 + \beta_{41} y_4 + \beta_{51} y_5 + \epsilon_1 \]
\[ y_2 = \beta_{12} y_1 + \beta_{32} y_3 + \beta_{42} y_4 + \beta_{52} y_5 + \epsilon_2 \]
\[ y_3 = \beta_{13} y_1 + \beta_{23} y_2 + \beta_{43} y_4 + \beta_{53} y_5 + \epsilon_3 \]
\[ y_4 = \beta_{14} y_1 + \beta_{24} y_2 + \beta_{34} y_3 + \beta_{54} y_5 + \epsilon_4 \]
\[ y_5 = \beta_{15} y_1 + \beta_{25} y_2 + \beta_{35} y_3 + \beta_{45} y_5 + \epsilon_4 \]

where \( \beta_{ji} \) is the effect of pollution of region \( j \) on region \( i \).
Spatial Dependence

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where \( \beta_{ji} \) is the effect of pollution of region \( j \) on region \( i \).

What is the problem with this modeling strategy?
Spatial Dependence

Under standard econometric modeling, it is impossible to model spatial dependency.
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Spatial Autocorrelation

- Autocorrelation \(\Rightarrow\) the correlation of a variable with itself
Spatial Autocorrelation

- **Autocorrelation** $\iff$ the correlation of a variables with itself
  - Time series: the values of a variable at time $t$ depends on the value of the same variable at time $t - 1$. 
Spatial Autocorrelation

- **Autocorrelation** $\Rightarrow$ the correlation of a variable with itself
  - Time series: the values of a variable at time $t$ depends on the value of the same variable at time $t - 1$.
  - Space: the correlation between the value of the variable at two different locations.
Spatial Autocorrelation

- **Autocorrelation** ⇒ the correlation of a variable with itself
  - **Time series**: the values of a variable at time $t$ depends on the value of the same variable at time $t - 1$.
  - **Space**: the correlation between the value of the variable at two different locations.

**Definition (Spatial Autocorrelation)**

- Correlation between the same attribute at two (or more) different locations.
- Coincidence of values similarity with location similarity.
- Under spatial dependency it is not possible to change the location of the values of certain variable without affecting the information in the sample.
- It can be positive and negative.
Spatial Autocorrelation

**Definition (Positive Autocorrelation)**

Observations with high (or low) values of a variable tend to be clustered in space.
Spatial Autocorrelation

**Definition (Positive Autocorrelation)**

Observations with high (or low) values of a variable tend to be clustered in space.

**Figure:** Positive Autocorrelation

```
1  1
1  1
1  1
```
Spatial Autocorrelation

Definition (Negative Autocorrelation)

Locations tend to be surrounded by neighbors having very dissimilar values.
Spatial Autocorrelation

Definition (Negative Autocorrelation)

Locations tend to be surrounded by neighbors having very dissimilar values.

Figure: Negative Autocorrelation

1 1 1
1 1 1
1 1 1
Spatial Autocorrelation: Another Example

Positive Spatial Autocorrelation

Negative Spatial Autocorrelation
Spatial Autocorrelation

Definition (Spatial Randomness)
When none of the two situations occurs.
Spatial Autocorrelation

Two main sources of spatial autocorrelation (Anselin, 1988):
- Measurement errors.
- Importance of Space.

The second source is of much more interest.

Figure: Professor Luc Anselin
Why the space matters?

- The essence of regional sciences and new economic geography is that location and distance matter.
- What is observed at one point is determined by what happen elsewhere in the system.
First Law of Geography Again

Tobler’s First Law of Geography

Everything depends on everything else, but closer things more so

Important ideas:
First Law of Geography Again

Tobler’s First Law of Geography

*Everything depends on everything else, but closer things more so*

- Important ideas:
  - **Existence** of Spatial Dependence.
First Law of Geography Again

Tobler’s First Law of Geography

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- Important ideas:
  - **Existence** of Spatial Dependence.
  - **Structure** of Spatial Dependence
First Law of Geography Again

Tobler’s First Law of Geography

*Everything depends on everything else, but closer things more so*

Important ideas:

- **Existence** of Spatial Dependence.
- **Structure** of Spatial Dependence
  - Distance decay.
Tobler’s First Law of Geography

*Everything depends on everything else, but closer things more so*

- Important ideas:
  - **Existence** of Spatial Dependence.
  - **Structure** of Spatial Dependence
    - Distance decay.
    - Closeness = Similarities.
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Spatial Weight Matrix

One crucial issue in spatial econometric is the problem of formally incorporating spatial dependence into the model.
Spatial Weight Matrix

One crucial issue in spatial econometric is the problem of formally incorporating spatial dependence into the model.

Question?

What would be a good criteria to define closeness in space? Or, in other words, how to determine which other units in the system influence the one under consideration?
Spatial Weight Matrix

- The device typically used in spatial analysis is the so-called spatial weight matrix, or simply $W$ matrix.
- Impose a structure in terms of what are the neighbors for each location.
- Assigns weights that measure the intensity of the relationship among pair of spatial units.
- Not necessarily symmetric.
Spatial Weight Matrix

Definition (W Matrix)

Let \( n \) be the number of spatial units. The spatial weight matrix, \( W \), a \( n \times n \) positive symmetric and non-stochastic matrix with element \( w_{ij} \) at location \( i, j \). The values of \( w_{ij} \) or the weights for each pair of locations are assigned by some preset rules which defines the spatial relations among locations. By convention, \( w_{ij} = 0 \) for the diagonal elements.

The symmetry assumption can be dropped later.

\[
W = \begin{pmatrix}
w_{11} & w_{12} & \cdots & w_{1n} \\
w_{21} & w_{22} & \cdots & w_{2n} \\
\vdots & \vdots & \ddots & \vdots \\
w_{n1} & w_{n2} & \cdots & w_{nn}
\end{pmatrix}
\]
Spatial Weight Matrix

Two main approaches:

1. Contiguity.
2. Based on distance
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The availability of polygon or lattice data permits the construction of contiguity-based spatial weight matrices. A typical specification of the contiguity relationship in the spatial weight matrix is

\[ w_{ij} = \begin{cases} 
1 & \text{if } i \text{ and } j \text{ are contiguous} \\
0 & \text{if } i \text{ and } j \text{ are not contiguous} 
\end{cases} \]  

(2)

**Binary Contiguity:**
- Rook criterion (Common Border)
- Bishop criterion (Common Vertex)
- Queen criterion (Either common border or vertex)
Rook Contiguity

How are the neighbors of region 5?

**Figure:** Rook Contiguity

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>4</td>
<td>5</td>
<td>6</td>
</tr>
<tr>
<td>7</td>
<td>8</td>
<td>9</td>
</tr>
</tbody>
</table>
Figure: Rook Contiguity

Common border: 2, 4, 5, 6
Figure: Rook Contiguity

Common border: 2, 4, 5, 6
Bishop Contiguity

**Figure:** Bishop Contiguity

\[
\begin{array}{ccc}
1 & 2 & 3 \\
4 & 5 & 6 \\
7 & 8 & 9 \\
\end{array}
\]
Bishop Contiguity

**Figure:** Bishop Contiguity

<table>
<thead>
<tr>
<th></th>
<th>1</th>
<th>2</th>
<th>3</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td></td>
<td>5</td>
<td>6</td>
</tr>
<tr>
<td>7</td>
<td></td>
<td>8</td>
<td>9</td>
</tr>
</tbody>
</table>

Common vertex: 1, 3, 7, 9
Queen Contiguity

**Figure:** Queen Contiguity

```
1  2  3  
4  5  6  
7  8  9  
```
Queen Contiguity

**Figure:** Queen Contiguity

```
  1   2   3   
  4   5   6   
  7   8   9   
```

Common vertex and border: 1, 2, 3, 4, 6, 7, 8, 9.
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Rook Contiguity

\[
W = \begin{pmatrix}
0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 \\
0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 \\
0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 1 \\
0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 1 \\
0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\
\end{pmatrix}
\]
Bishop Contiguity

\[
W = \begin{pmatrix}
0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\
1 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 1 \\
0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
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Weights may be also defined as a function of the distance between region \(i\) and \(j\), \(d_{ij}\).

\(d_{ij}\) is usually computed as the distance between their centroids (or other important unit).

Let \(x_i\) an \(x_j\) be the longitud and \(y_i\) and \(y_j\) the latitude coordinates for region \(i\) and \(j\), respectively:
Distance Metric

**Definition (Minkowski metric)**

Let two points \(i\) and \(j\), with respective coordinates \((x_i, y_i)\) and \((x_j, y_j)\):

\[
d^p_{ij} = (|x_i - x_j|^p + |y_i - y_j|^p)^{1/p}
\]  (3)

**Definition (Euclidean metric)**

Consider Minkowski metric and set \(p = 2\), then

\[
d^e_{ij} = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}.
\]  (4)

**Definition (Manhattan metric)**

Consider Minkowski metric and set \(p = 1\), then

\[
d^m_{ij} = |x_i - x_j| + |y_i - y_j|.
\]  (5)
Euclidean distance is not necessarily the shortest distance if you take into account the curvature of the earth.

**Definition (Great Circle Distance)**

Let two points \(i\) and \(j\), with respective coordinates \((x_i, y_i)\) and \((x_j, y_j)\):

\[
d_{ij}^{cd} = r \times \arccos^{-1} \left[ \cos |x_i - x_j| \cos y_i \cos y_j + \sin y_i \sin y_j \right]
\]

where \(r\) is the Earth’s radius. The arc distance is obtained in miles with \(r = 3959\) and in kilometers with \(r = 6371\).
Inverse distance:

\[
   w_{ij} = \begin{cases} 
   \frac{1}{d_{ij}^\alpha} & \text{if } i \neq j \\
   0 & \text{if } i = j 
   \end{cases}
\]  

Typically, \( \alpha = 1 \) or \( \alpha = 2 \).

Negative exponential model:

\[
   w_{ij} = \exp \left( -\frac{d_{ij}}{\alpha} \right)
\]
**W based on distance**

- **k-nearest neighbors**: We explicitly limit the number of neighbors.

\[ w_{ij} = \begin{cases} 
1 & \text{if centroid of } j \text{ is one of the } k \text{ nearest centroids to that of } i \\
0 & \text{otherwise} 
\end{cases} \]  

(9)

- **Threshold Distance (Distance Band Weights)**: In contrast to the k-nearest neighbors method, the threshold distance specifies that an region i is neighbor of j if the distance between them is less than a specified maximum distance:

\[ w_{ij} = \begin{cases} 
1 & \text{if } 0 \leq d_{ij} \leq d_{\text{max}} \\
0 & \text{if } d_{ij} > d_{\text{max}} 
\end{cases} \]  

(10)

To avoid isolates that would result from too stringent a critical distance, the distance must be chosen such that each location has at least one neighbor. Such a distance conforms to a max-min criterion, i.e., it is the largest of the nearest neighbor distances.
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Row standardization

- **W**’s are used to compute **weighted averages** in which more weight is placed on nearby observations than on distant observations.
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The elements of a row-standardized weights matrix equal

\[ w_{ij}^s = \frac{w_{ij}}{\sum_j w_{ij}}. \]

This ensures that all weights are between 0 and 1 and facilitates the interpretation of operation with the weights matrix as an averaging of neighboring values.
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- Under row-standardization, the element of each row sum to unity.
- The row-standardized weights matrix also ensures that the spatial parameter in many spatial stochastic processes are comparable between models.
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- Under row-standardization, the element of each row sum to unity.
- The row-standardized weights matrix also ensures that the spatial parameter in many spatial stochastic processes are comparable between models.
- Under row-standardization the matrices are not longer symmetric!
Row standardization

The row-standardized matrix is also known in the literature as the row-stochastic matrix:

Definition (Row-stochastic Matrix)

A real $n \times n$ matrix $A$ is called Markov matrix, or row-stochastic matrix if

1. $a_{ij} \geq 0$ for $1 \leq i, j \leq n$;
2. $\sum_{j=1}^{n} a_{ij} = 1$ for $1 \leq i \leq n$

An important characteristic of the row-stochastic matrix is related to its eigenvalues:

Theorem (Eigenvalues of row-stochastic Matrix)

Every eigenvalue $\omega_i$ of a row-stochastic Matrix satisfies $|\omega| \leq 1$

Therefore, the eigenvalues of the row-stochastic (i.e., row-normalized, row standardized or Markov) neighborhood matrix $W^s$ are in the range $[-1, +1]$. 
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Spatial Lag

The spatial lag operator takes the form $y_L = Wy$ with dimension $n \times 1$, where each element is given by $y_{Li} = \sum_j w_{ij} y_j$, i.e., a weighted average of the $y$ values in the neighbor of $i$.

For example:

$$Wy = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 10 \\ 50 \\ 30 \end{pmatrix} = \begin{pmatrix} 50 \\ 10 + 30 \\ 50 \end{pmatrix} \tag{11}$$

Using a row-standardized weight matrix:

$$W^s y = \begin{pmatrix} 0 & 1 & 0 \\ 0.5 & 0 & 0.5 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 10 \\ 50 \\ 30 \end{pmatrix} = \begin{pmatrix} 50 \\ 5 + 15 \\ 50 \end{pmatrix} \tag{12}$$

Therefore, when $W$ is standardized, each element $(Wy)_i$ is interpreted as a weighted average of the $y$ values for $i$'s neighbors.
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- Row Standardization
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How to define higher-order neighbors?

- We might be interested in the neighbors of the neighbors of spatial unit \( i \).
- We define the higher-order spatial weigh matrix \( l \) as \( W^l \).
  - Spatial weight of order \( l = 2 \) is given by \( W^2 = WW \).
  - Spatial weight of order \( l = 3 \) is given by \( W^3 = WWW \).
- As an illustration consider the following structure for our previous example:

\[
W = \begin{pmatrix}
0 & 1 & 0 & 0 & 0 \\
1 & 0 & 1 & 0 & 0 \\
0 & 1 & 0 & 1 & 0 \\
0 & 0 & 1 & 0 & 1 \\
0 & 0 & 0 & 1 & 0 \\
\end{pmatrix}
\]
Higher-Order Neighbors

Then $W^2 = WW$ based on the $5 \times 5$ first-order contiguity matrix $W$ from (13) is:

$$W^2 = \begin{pmatrix} 1 & 0 & 1 & 0 & 0 \\ 0 & 2 & 0 & 1 & 0 \\ 1 & 0 & 2 & 0 & 1 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{pmatrix}$$ (14)

Figure: Higher-Order Neighbors
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Creating spatial weight matrices by hand is tedious (and almost impossible).

However, there exists several statistical software that allow us to create them in a very simply fashion.

First, we need the **shape file**, which has geographical information:
- It is a digital vector storage for storing geometric location and associated attribute information

**Mandatory files:**
- `.shp`: shape format; the feature geometry itself,
- `.shx`: shape index format; a positional index of the feature geometry to allow seeking forwards and backwards quickly,
- `.dbf`: attribute format; columnar attributes for each shape, in dBase IV format.
library("maptools")

If the shape file `mr_chile.shp` is in the same folder, then we can load it into R using the command `readShapeSpatial`:

```r
setwd("~/Dropbox/Mis Clases/Spatial Econometrics/Children")
mr <- readShapeSpatial("mr_chile.shp")
```

```r
## Warning: readShapeSpatial is deprecated; use rgdal::readOGR or sf::st_read
## Warning: readShapePoly is deprecated; use rgdal::readOGR or sf::st_read

class(mr)
```

```r
## [1] "SpatialPolygonsDataFrame"
## attr(,"package")
## [1] "sp"
```

The function `readShapeSpatial` reads data from the shapefile into a Spatial object of class "sp". The function `names` give us the name of the variables in the `.dbf` file associated with the shape file.

```r
names(mr)
```

```r
## [1] "ID" "NAME" "NAME2" "URB_POP" "RUR_POP"
## [6] "MALE_POP" "TOT_POP" "FEM_POP" "N_PARKS" "N_PLAZA"
## [11] "CONS_HOUSE" "M2CONS_HA" "GREEN_AREA" "AREA" "POVERTY"
```
plot(mr, main = "Metropolitan Region–Chile", axes = TRUE)
To create spatial weight matrices we need to use the `spdep` package

```r
library("spdep")
```

In the `spdep` package, neighbor relationships between $n$ observations are represented by an object of class “nb”.

The function `poly2nb` is used in order to construct weight matrices based on contiguity.

First, we create a neighbor list based on the ‘Queen’ criteria for the communes of the Metropolitan Region:

```r
queen.w <- poly2nb(mr, row.names = mr$NAME, queen = TRUE)
```
```r
summary(queen.w)

## Neighbour list object:
## Number of regions: 52
## Number of nonzero links: 292
## Percentage nonzero weights: 10.79882
## Average number of links: 5.615385
## Link number distribution:
##
##  2  3  4  5  6  7  8  9 10 12
##  3  2  7 15 10 10  2  1  1  1
## 3 least connected regions:
## Tiltiil San Pedro Maria Pinto with 2 links
## 1 most connected region:
## San Bernardo with 12 links
```
To transform the list into an actual matrix $W$, we can use the function `nb2listw`:

```r
queen.wl <- nb2listw(queen.w, style = "W")
summary(queen.wl)
```

## Characteristics of weights list object:
## Neighbour list object:
## Number of regions: 52
## Number of nonzero links: 292
## Percentage nonzero weights: 10.79882
## Average number of links: 5.615385
## Link number distribution:
##
## 2 3 4 5 6 7 8 9 10 12
## 3 2 7 15 10 10 2 1 1 1
## 3 least connected regions:
## Tiltit San Pedro Maria Pinto with 2 links
## 1 most connected region:
## San Bernardo with 12 links
##
## Weights style: W
## Weights constants summary:
## n  nn  S0  S1  S2
## W 52 2704 52 19.76751 216.466
Now, we construct a binary matrix using the Rook criteria:

```r
# Rook W
rook.w <- poly2nb(mr, row.names = mr$NAME, queen = FALSE)
summary(rook.w)
```

```
## Neighbour list object:
## Number of regions: 52
## Number of nonzero links: 272
## Percentage nonzero weights: 10.05917
## Average number of links: 5.230769
## Link number distribution:
##
## 2 3 4 5 6 7 8 9 10
## 3 3 12 16 7 6 2 1 2
## 3 least connected regions:
## Tiltil San Pedro Maria Pinto with 2 links
## 2 most connected regions:
## Santiago San Bernardo with 10 links
```
Finally, we can plot the weight matrices using the following set of commands:

```r
# Plot Queen and Rook W Matrices
plot(mr, border = "grey")
plot(queen.w, coordinates(mr), add = TRUE, col = "red")
plot(rook.w, coordinates(mr), add = TRUE, col = "yellow")
```
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First, we extract coordinates: We now construct spatial weight matrices using the \( k \)-nearest neighbors criteria.

```r
# K-neighbors
coords <- coordinates(mr) # coordinates of centroids
head(coords, 5) # show coordinates

## [,1]          [,2]
## 0  -70.65599   -33.45406
## 1  -70.71742   -33.50027
## 2  -70.74504   -33.42278
## 3  -70.67735   -33.38372
## 4  -70.67640   -33.56294

k1neigh <- knearneigh(coords, k = 1, longlat = TRUE) # 1-nearest neighbor
k2neigh <- knearneigh(coords, k = 2, longlat = TRUE) # 2-nearest neighbor
```

- The function `coords` extract the spatial coordinates from the shape file, whereas the function `knearneigh` return a matrix with the indices of points belonging to the set of the \( k \)-nearest neighbors of each other.
- The argument `k` indicates the number of nearest neighbors to be returned.
- If point coordinates are longitude-latitude decimal degrees, then distances are measured in kilometers if `longlat = TRUE`, if `TRUE` great circle distances are used.
- Objects `k1neigh` and `k2neigh` are of class `knn`. 
Weight matrices based on inverse distance can be computed in the following way:

```r
# Inverse weight matrix
dist.mat <- as.matrix(dist(coords, method = "euclidean"))
dist.mat[1:5, 1:5]

## 0 1 2 3 4
## 0 0.000000 0.07687010 0.09438408 0.07350782 0.11078109
## 1 0.07687010 0.00000000 0.08226867 0.12324109 0.07489489
## 2 0.09438408 0.08226867 0.00000000 0.07814455 0.15606360
## 3 0.07350782 0.12324109 0.07814455 0.00000000 0.17922003
## 4 0.11078109 0.07489489 0.15606360 0.17922003 0.00000000

dist.mat.inv <- 1 / dist.mat  # 1 / d_{ij}
diag(dist.mat.inv) <- 0        # 0 in the diagonal
dist.mat.inv[1:5, 1:5]

## 0 1 2 3 4
## 0 0.000000 13.008960 10.595007 13.603994 9.026811
## 1 13.008960 0.000000 12.155295 8.114177 13.352046
## 2 10.595007 12.155295 0.000000 12.796797 6.407644
## 3 13.603994 8.114177 12.796797 0.000000 5.579733
## 4 9.026811 13.352046 6.407644 5.579733 0.000000
```
```r
# Standardized inverse weight matrix
dist.mat.inve <- mat2listw(dist.mat.inv, style = "W", row.names = mr$NAME)
summary(dist.mat.inve)

## Characteristics of weights list object:
## Neighbour list object:
## Number of regions: 52
## Number of nonzero links: 2652
## Percentage nonzero weights: 98.07692
## Average number of links: 51
## Link number distribution:
##
## 51
## 52
## 52 least connected regions:
## Santiago Cerillos Cerro Navia Conchali El Bosque Estacion Central La Cisterna La
## 52 most connected regions:
## Santiago Cerillos Cerro Navia Conchali El Bosque Estacion Central La Cisterna La
##
## Weights style: W
## Weights constants summary:
## n  nn  S0  S1  S2
## W 52 2704 52 2.902384 214.3332
```
W in R

Queen

1–Neigh

2–Neigh

Inverse Distance
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Global Autocorrelation

- Indicators of spatial association
  1. Global Autocorrelation
  2. Local Autocorrelation

**Definition (Global Autocorrelation)**

It is a measure of overall clustering in the data. It yields only one statistic to summarize the whole study area (Homogeneity).

1. Moran’s I.
2. Gery’s C.
3. Getis and Ord’s $G(d)$

**Definition (Local Autocorrelation)**

A measure of spatial autocorrelation for each individual location.

- Local Indices for spatial Spatial Analysis (LISA)
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Moran’s I

This statistic is given by:

\[ I = \frac{\sum_{i=1}^{n} \sum_{j=1, j \neq i}^{n} w_{ij} (x_i - \bar{x}) (x_j - \bar{x})}{S_0 \sum_{i=1}^{n} (x_i - \bar{x})^2 / n} = \frac{n \sum_{i=1}^{n} \sum_{j=1}^{n} w_{ij} (x_i - \bar{x}) (x_j - \bar{x})}{S_0 \sum_{i=1}^{n} (x_i - \bar{x})^2} \]

(15)

where \( S_0 = \sum_{i=1}^{n} \sum_{j=1}^{n} w_{ij} \) and \( w_{ij} \) is an element of the spatial weight matrix that measures spatial distance or connectivity between regions \( i \) and \( j \). In matrix form:

\[ I = \frac{n}{S_0} \frac{z'Wz}{z'z} \]

(16)

where \( z = x - \bar{x} \). If the \( W \) matrix is row standardized, then:

\[ I = \frac{z'W^s z}{z'z} \]

(17)

because \( S_0 = n \). Values range from -1 (perfect dispersion) to +1 (perfect correlation). A zero value indicates a random spatial pattern.
Moran Scatterplot

- A very useful tool for understanding the Moran’s I test
Moran’s I

Note that:

\[ \hat{\beta}_{OLS} = \frac{\sum_i (x_i - \bar{x})(y_i - \bar{y})}{\sum_i (x_i - \bar{x})^2} \]

Therefore?
Moran’s I

Note that:

\[ \hat{\beta}_{OLS} = \frac{\sum_i (x_i - \bar{x})(y_i - \bar{y})}{\sum_i (x_i - \bar{x})^2} \]

Therefore?

Remark

\( I \) is equivalent to the slope coefficient of a linear regression of the spatial lag \( Wx \) on the observation vector \( x \) measured in deviation from their means. It is, however, not equivalent to the slope of \( x \) on \( Wx \) which would be a more natural way.
Moran’s $I$

- $H_0$: $x$ is spatially independent, the observed $x$ are assigned at random among locations. ($I$ is close to zero)
- $H_1$: $X$ is not spatially independent. ($I$ is not zero)
Moran’s I

- We are interested in the distribution of the following statistic:

\[ T_I = \frac{I - \mathbb{E}(I)}{\sqrt{\text{Var}(I)}} \]  

(18)

- Three approaches to compute the variance of Moran’s I:
  - Monte Carlo
  - Normality of \( x_i \): It is assumed that the random variable \( x_i \) are the result of \( n \) independently drawings from a normal population.
  - Randomization of \( x_i \): No matter what the underlying distribution of the population, we consider the observed values of \( x_i \) were repeatedly randomly permuted.
Moran’s I

Theorem (Moran’s $I$ Under Normality)

Assume that \( \{x_i\} = \{x_1, x_2, ..., x_n\} \) are independent and distributed as \( \text{N}(\mu, \sigma^2) \), but \( \mu \) and \( \sigma^2 \) are unknown. Then:

\[
\mathbb{E} (I) = -\frac{1}{n-1} \quad \text{(19)}
\]

and

\[
\mathbb{E} (I^2) = \frac{n^2 S_1 - nS_2 + 3S_0^2}{S_0^2(n^2 - 1)} \quad \text{(20)}
\]

where \( S_0 = \sum_{i=1}^{n} \sum_{j=1}^{n} w_{ij} \), \( S_1 = \sum_{i=1}^{n} \sum_{j=1}^{n} (w_{ij} + w_{ji})^2 / 2 \), \( S_2 = \sum_{i=1}^{n} (w_i + w_{i.})^2 \), where \( w_i. = \sum_{j=1}^{n} w_{ij} \) and \( w_{.i} = \sum_{j=1}^{n} w_{ji} \)

Then:

\[
\text{Var} (I) = \mathbb{E} (I^2) - \mathbb{E} (I)^2 \quad \text{(21)}
\]
Moran’s I

Theorem 17 gives the moments of Moran’s I under randomization.

**Theorem (Moran’s I Under Randomization)**

Under permutation, we have:

\[
\mathbb{E} (I) = -\frac{1}{n - 1} \quad (22)
\]

and

\[
\mathbb{E} (I^2) = \frac{n \left[ (n^2 - 3n + 3) S_1 - nS_2 + 3S_0^2 \right] - b_2 \left[ (n^2 - n) S_1 - 2nS_2 + 6S_0^2 \right]}{(n - 1)(n - 2)(n - 3)S_0^2} \quad (23)
\]

where \( S_0 = \sum_{i=1}^{n} \sum_{j=1}^{n} w_{ij} \), \( S_1 = \sum_{i=1}^{n} \sum_{j=1}^{n} (w_{ij} + w_{ji})^2 / 2 \), \( S_2 = \sum_{i=1}^{n} (w_i. + w_.i)^2 \), where \( w_i. = \sum_{j=1}^{n} w_{ij} \) and \( w_.i = \sum_{j=1}^{n} w_{ji} \). Then:

\[
\text{Var} (I) = \mathbb{E} (I^2) - \mathbb{E} (I)^2 \quad (24)
\]

It is important to note that the expected value of Moran’s I under normality and randomization is the same.
Monte Carlo

- Normality and randomization? We can use a Monte Carlo simulation
  - To test a null hypothesis $H_0$ we specify a test statistic $T$ such that large values of $T$ are evidence against $H_0$.
    - $H_0$: no spatial autocorrelation.
  - Let $T$ have observed value $t_{obs}$. We generally want to calculate:
    $$ p = \Pr(T \geq t_{obs} | H_0) $$
    (25)
  - We need the distribution of $T$ when $H_0$ is true to evaluate this probability.
Sampling distribution when $H_0$ is true

$P$-value

Observed statistic
Monte Carlo

Theorem (Moran’s’ I Monte Carlo Test)

The procedure is the following:

1. Rearrange the spatial data by shuffling their location and compute the Moran’s I $S$ times. This will create the distribution under $H_0$.

2. Let $I_1^*, I_2^*, ..., I_S^*$ be the Moran’s I for each time. A consistent Monte Carlo $p$-value is then:

$$
\hat{p} = \frac{1 + \sum_{s=1}^{S} 1(I_s^* \geq I_{obs})}{S + 1}
$$

(26)

3. For tests at the $\alpha$ level or at $100(1 - \alpha)$% confidence intervals, there are reasons for choosing $S$ so that $\alpha(S + 1)$ is an integer. For example, use $S = 999$ for confidence intervals and hypothesis tests when $\alpha = 0.05$. 


Inference:

- If $I > \mathbb{E}(I)$, then a spatial unit tends to be connected by locations with similar attributes: Spatial clustering (low/low or high/high). The strength of positive spatial autocorrelation tends to increase with $I - \mathbb{E}(I)$.
- If $I < \mathbb{E}(I)$ observations will tend to have dissimilar values from their neighbors: Negative spatial autocorrelation (low/high or high/low)
Application

- Lab1A.R
- Lab1B.R